

A experimental European multi-site deep-space optical study

Dick, J., Herridge, P.
Observatory Sciences Ltd., United Kingdom

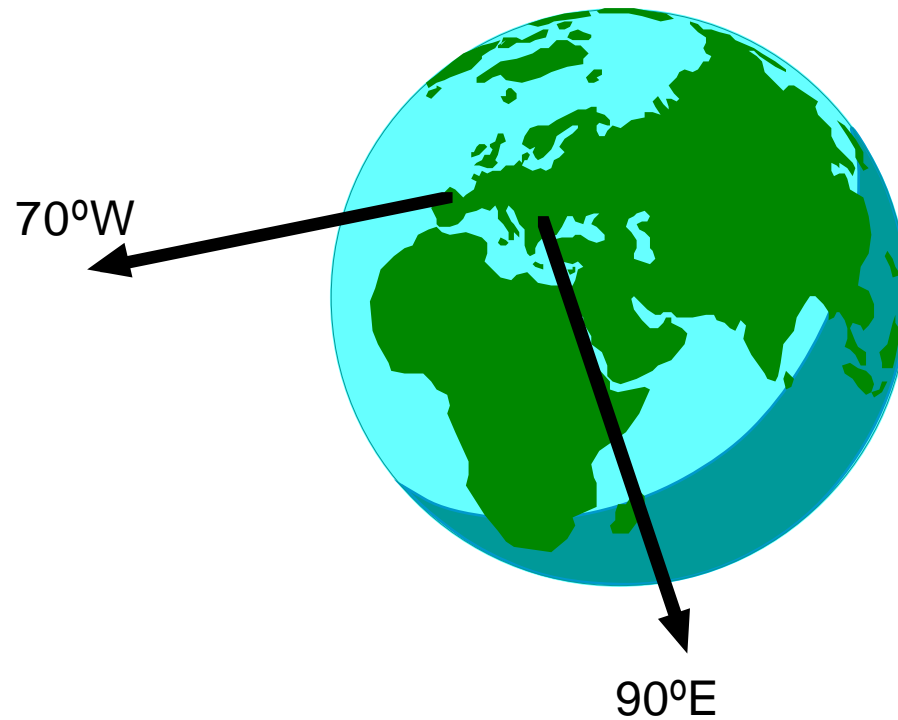
Schildknecht, T., Ploner, M.,
Astronomical Institute, University of Bern, Switzerland

Bain, M., Holland, D.,
Ministry of Defence, United Kingdom



Thinking about deep-space surveillance. . .

Coverage, sensor type, & catalogue maintenance



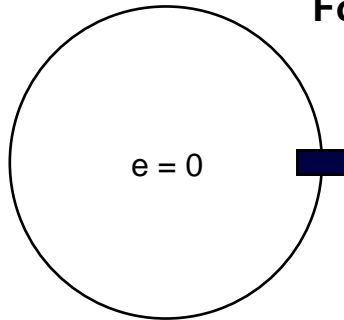
Radar: No weather problems
Good r and dr/dt
Possible imaging information
but
Expensive
 r^{-4} sensitivity law
Small field of view in deep-space

Optics: Weather problems
Poor orbits from short-arcs
but
Not expensive
 r^{-2} sensitivity law
Large field of view in deep-space

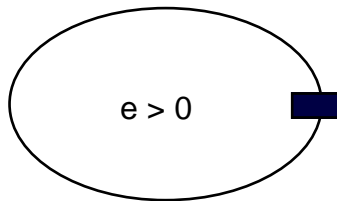
Catalogue maintenance:
Good detection & large volume
Good orbits

The optics and orbits problem . . .

For short-arc observations (typical of surveillance/ debris searches)



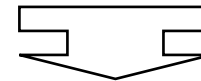
- Semi-major axis (a) ✓
- Plane of orbit (i, Ω) ✓
- Ellipticity (e, ω) Not applicable



- Semi-major axis (a) ?
 - Plane of orbit (i, Ω) ~ ✓
 - Ellipticity (e, ω) ✗
-

“No shows” during follow-up searches

Objects “discovered” more than once



Poor catalogue



The optics and orbits problem . . .

How to be misled: *try to fit a circular orbit*

Along-track error $\sim (v - M)^0 \sim 2 e \sin(M) + \dots \sim \pm 300 \delta e^0$ at worst

Orbit plane (i, Ω) error $\sim \text{some}^0$

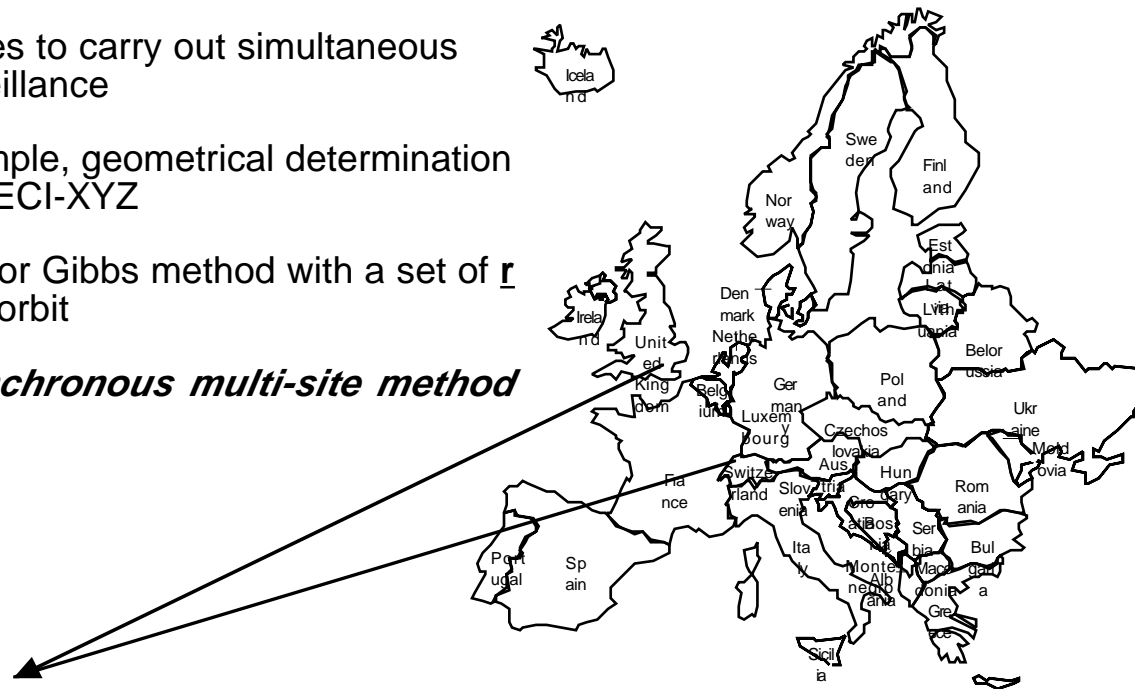
Semi-major axis (a) error $\sim \text{many}^0/\text{day}$

The optics and orbits problem . . .

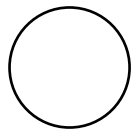
How to avoid being misled, part 1

- Use *two* sites to carry out simultaneous volume surveillance
- Obtain a simple, geometrical determination of object \underline{r} in ECI-XYZ
- Use Gauss or Gibbs method with a set of \underline{r} to determine orbit

. . . the synchronous multi-site method

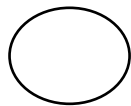


Modelling the method and assessing potential . . .



$e \sim 0$ Typical GEO payload

Circular orbit generally best; synchronous multi-site (SMS) track gives small, spurious eccentricity which is not a problem to detect.



$e \sim 0.01$ GEO debris

TEST CASE

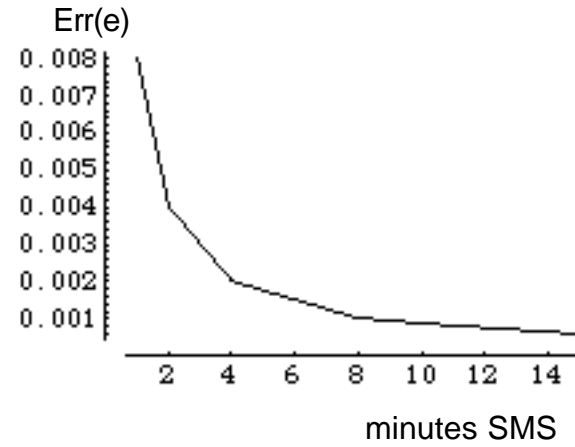
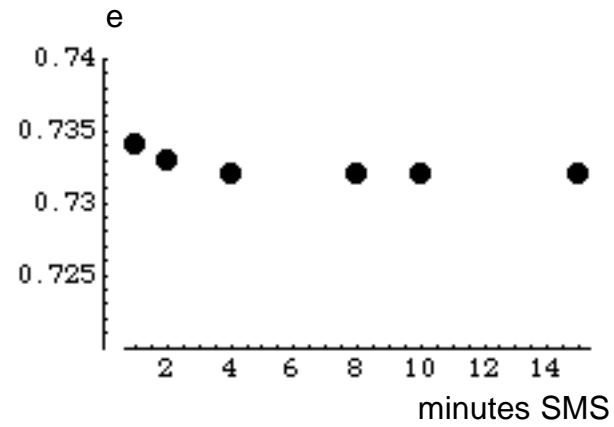


$e \sim 0.73$ Typical GTO

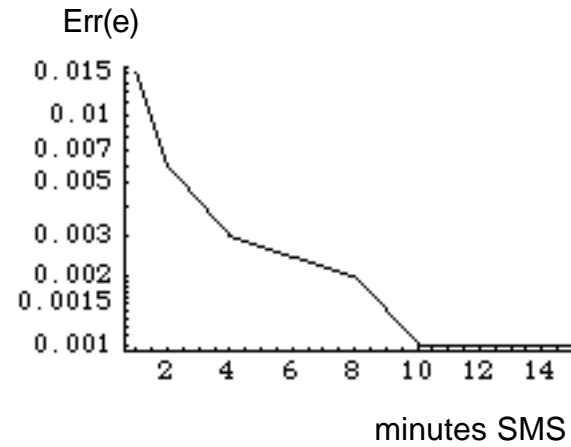
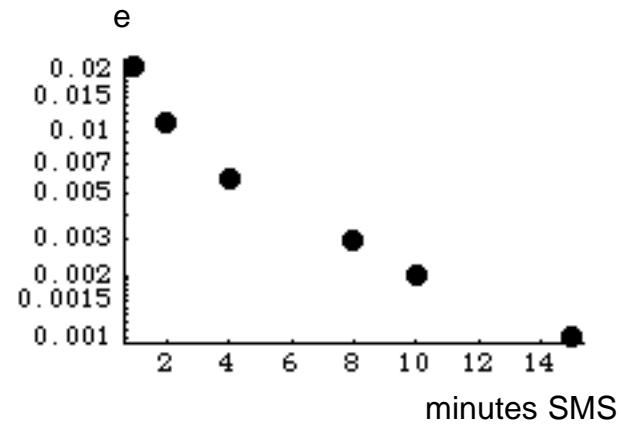
4 to 8 minutes SMS track gives excellent re-acquisition expectations

Eccentricity detection . . .

GTO

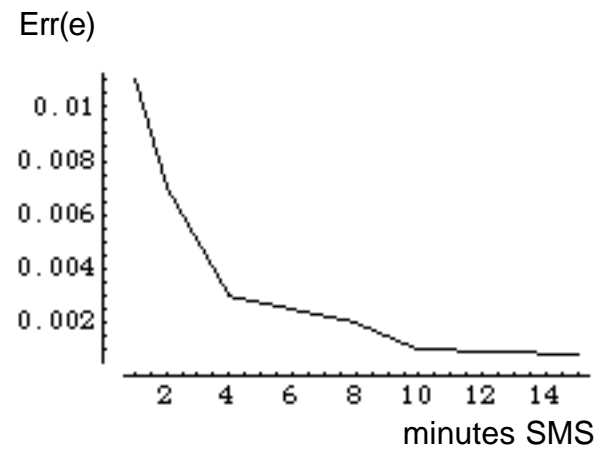
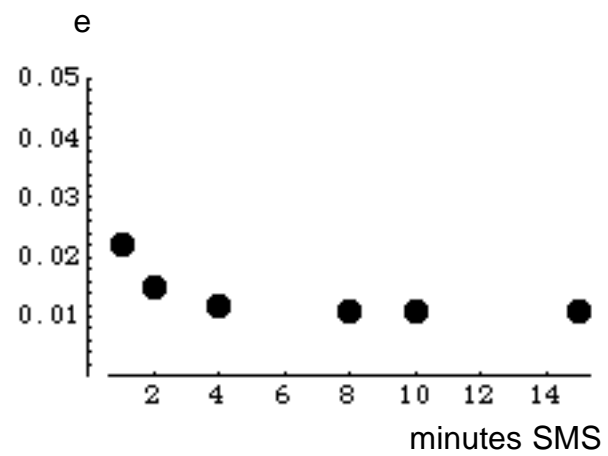


GEO

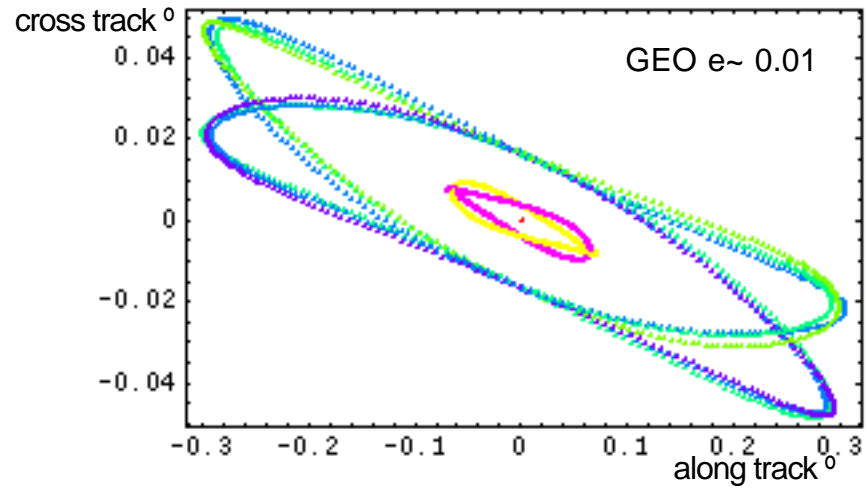


Eccentricity detection . . .continued

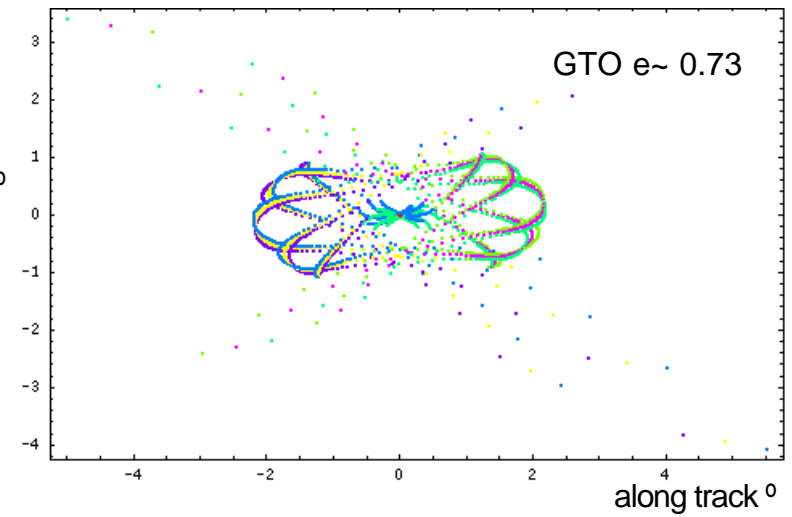
GEO
debris



Modelling the re-acquisition phase . . .



cross track^o

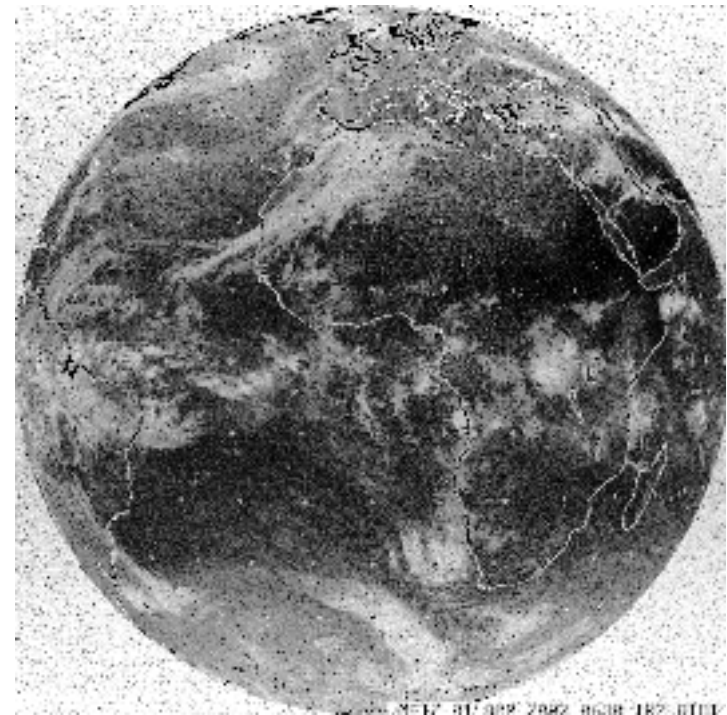


But is it feasible . . . ?

Europe has many potential co-operating sites
Common time from satellite or VLF system
Common Earth model for site position
Common communications via Internet or GSM



? Clear skies: distributed observing helps



But is it feasible . . . ?

We have carried out method trials using the 1m telescope at Zimmerwald and various members of the UK MoD's PIMS network





Trials – sensors used

Zimmerwald

alt-az “all orbits”-capable mount

1.0 m aperture

2k x 2k cooled scientific CCD

24 arc minute field of view

observer-driven

Switzerland

Astronomical Institute, University of Bern

Passive Imaging Metric System (PIMS)

alt-az GEO/GTO/MEO/HEO-capable mount

0.4 m aperture

1k x 1k cooled scientific CCD

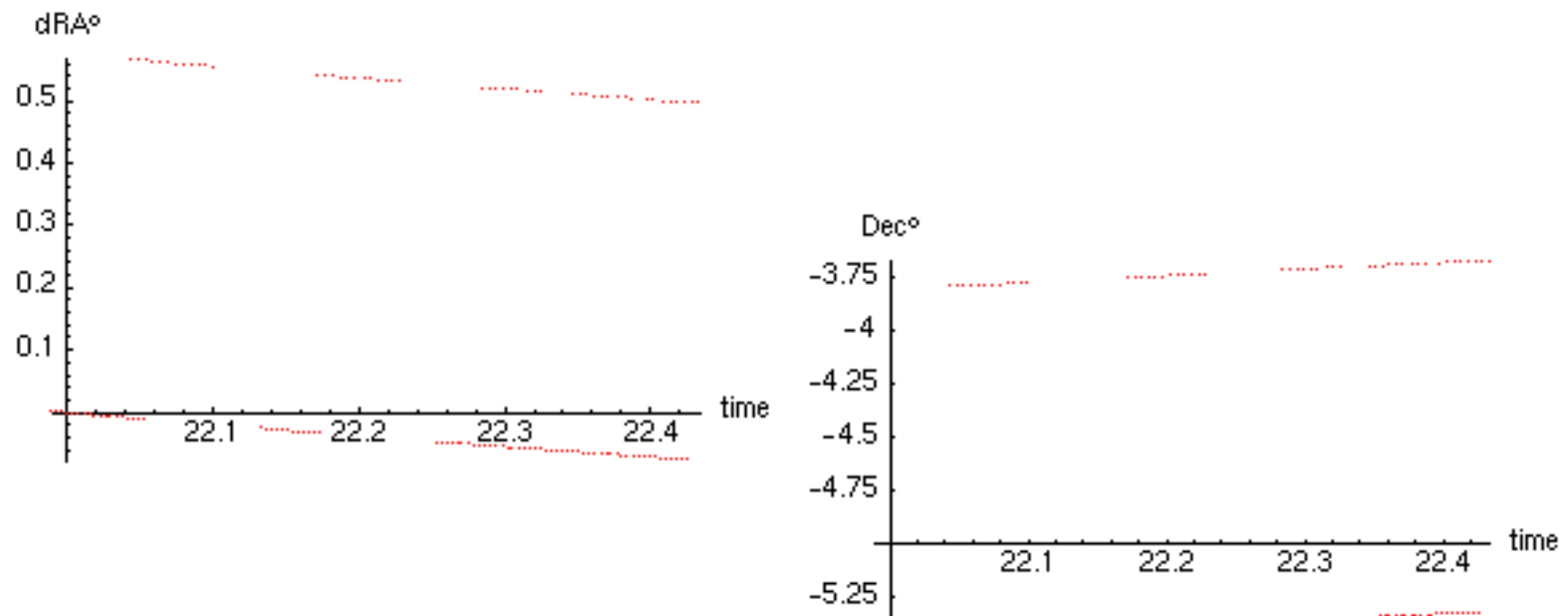
40 arc minute field of view

autonomous robotic system

Herstmonceux, Gibraltar, Cyprus

UK Ministry of Defence

Trials – observations from SMS tracking





Trials – results from SMS tracking

GEO payload example (1998-035-A)

Short-arc circular orbit is better than the SMS orbit.

GEO debris example (1999-047-E)

Short-arc circular orbit: $\sim 6^\circ/\text{day}$ drift – so object probably not able to be
re-acquired on the next night

SMS short-arc orbit: $\sim 0.7^\circ/\text{day}$ drift



The optics and orbits problem . . .

How to avoid being misled, part 2

Take long-arc tracks... and compute an elliptical orbit from the angles-only observations

OR

Take multi-site angles-only observations

. . . the asynchronous multi-site method



Summary

Multi-site tracking of objects enables optical sensors to detect even quite small eccentricities in found-object orbits.

The length of track necessary appears to be quite short – only a few minutes – to provide detection of even small (~ 0.01) eccentricities.

A trial has been successfully carried out.

The method benefits include...

- ...A cleaner catalogue – because of double-detection and better orbits.

- ...Follow-up observing is easier and less sensor time is wasted.



Acknowledgements

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